

$(\mathbb{R}^n)^\#$ SPAZIO DUALE in \mathbb{R}^n :

$(\mathbb{R}^n)^\# = \{ \varphi: \mathbb{R}^n \rightarrow \mathbb{R}; \varphi \text{ lineare} \}, +, \cdot$ are

LO ZERO in $(\mathbb{R}^n)^\#$ è:

$\underline{0}: \mathbb{R}^n \rightarrow \mathbb{R}$ lineare, $\underline{0}(x) = 0 \in \mathbb{R} \forall x \in \mathbb{R}^n$
 $\underline{0}$ è l'unica funzione nulla.

FUNZIONI "COORDINATE": $i=1, 2, \dots, n$

$d_{x_i}: \mathbb{R}^n \rightarrow \mathbb{R}$ lineare t.c.
 $d_{x_i}(e_j) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} = \delta_{ij} = \int_{j=1, \dots, n}^{n \text{ coordinate}}$

Quindi $d_{x_i} \in (\mathbb{R}^n)^\#$, $\forall i=1, 2, \dots, n$.

ora $\forall v = (v_1, v_2, \dots, v_n) \in \mathbb{R}^n$

$$v = \sum_{j=1}^n v_j \cdot e_j \Rightarrow$$

$$d_{x_i}(v) = d_{x_i}\left(\sum_{j=1}^n v_j \cdot e_j\right) \stackrel{L.N.}{=} \sum_{j=1}^n v_j \cdot d_{x_i}(e_j) = v_i \quad !!!$$

THM L'INBIENTE

$\{d_{x_1}, d_{x_2}, \dots, d_{x_n}\}$ è BASE in $(\mathbb{R}^n)^\#$ | 1

na evi $\dim((\mathbb{R}^n)^\#) = \dim(\mathbb{R}^n) = n$.

PROOF

1) SISTEMA DI GENERATORI. Sia $\varphi \in (\mathbb{R}^n)^\#$

Sia $v = (v_1, \dots, v_n) \in \mathbb{R}^n$
 $\varphi(v) = \sum_{i=1}^n \varphi(e_i) \cdot v_i = \sum_{i=1}^n v_i \cdot d_{x_i}(v)$

CONSEGUENZE 1) $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}$ lineare;

COME SI SCRIVE φ $\varphi(v) = \varphi\left(\sum_{i=1}^n v_i \cdot e_i\right) = \sum_{i=1}^n v_i \cdot \varphi(e_i)$
MA TO $\varphi(e_i) = d_{x_i}(\varphi)$ come si scrive

$$d_{x_i}(\varphi) = \sum_{j=1}^n \varphi(e_j) \cdot d_{x_i}(e_j) = \varphi(e_i)$$

MA $d_{x_i}(v_1, v_2, \dots, v_n) = v_i$

QUINDI

$$\varphi(v_1, v_2, \dots, v_n) = \sum_{i=1}^n \varphi(e_i) \cdot v_i$$

L'INBIENTE: $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}$ lineare $\Leftrightarrow \varphi \in (\mathbb{R}^n)^\#$

$$\varphi: \mathbb{R}^n \rightarrow \mathbb{R}^m \quad \varphi(x) = \begin{pmatrix} \varphi_1(x) \\ \vdots \\ \varphi_m(x) \end{pmatrix}$$

$$\varphi(x) = \sum_{i=1}^m \varphi_i(x) e_i \quad e_i \in (\mathbb{R}^m)^*$$

CONSEGUENZE 1) $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}^m$ LINEARE

COME SI SCRIVE $\varphi \left(\sum_{i=1}^m \alpha_i e_i \right) = \sum_{i=1}^m \alpha_i \varphi(e_i)$

MA TU $\varphi(x) = \sum_{i=1}^m \alpha_i \varphi(e_i)$ $\forall x \in \mathbb{R}^n$

DA TU $d_x \varphi = \sum_{i=1}^m \alpha_i d_x \varphi(e_i)$ in $(\mathbb{R}^n)^*$

QUINDI

$$\varphi(x_1, \dots, x_n) = \sum_{i=1}^m \varphi(e_i) x_i$$

LINEARE: $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}^m$ LINEARE $\Leftrightarrow \exists \varphi \in (\mathbb{R}^n)^*$

COEFF. LINEARE $\varphi(x) = \sum_{i=1}^n c_i x_i$

COEFF. $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}$ LINEARE \Leftrightarrow
 φ SI SCRIVE COME POLINOMIO

QUADRATO DI GRADO 1 (QUINDI SENZA TERMINE NOTO!)

PROES IN $n=3$

i) $\varphi(x_1, x_2, x_3) = 2x_1 + 3x_2 + x_3$ LINEARE

ii) $\varphi(x_1, x_2, x_3) = 2x_1 + 3x_2 - x_3 + 1$ NON LINEARE

iii) $\varphi(x_1, x_2, x_3) = x_1 x_2 + x_2 - x_3$ NON LINEARE

CASO PART. PER $n=1$

0 $\varphi: \mathbb{R} \rightarrow \mathbb{R}$ LINEARE \Leftrightarrow

$\varphi(x) = \sum_{i=1}^1 \alpha_i x_i$ (O SPARANO CIA'...)

$\varphi: \mathbb{R} \rightarrow \mathbb{R}$ LINEARE $\Leftrightarrow \exists \alpha \in \mathbb{R} \varphi(x) = \alpha x$ $x \in \mathbb{R}$

$= \sum_{i=1}^1 \frac{\partial \varphi}{\partial x_i}(x) dx_i$ α cost.

CONSEGUENZE (CASO ESEMPIO) $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}$

$\varphi: A \in \mathbb{R}^n \rightarrow \mathbb{R}$, A MATRICE COEFFICIENTI

DEFINIZIONE $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}$ LINEARE $\Leftrightarrow \exists A \in \mathbb{R}^n$ $\varphi(x) = Ax$

ES. $\varphi: \mathbb{R}^3 \rightarrow \mathbb{R}$ LINEARE $\varphi(x, y, z) = 3x^2 + xy^2 + 3z$

PROPRIETA' \Rightarrow φ LINEARE $\Leftrightarrow \varphi$ POLINOMIO DI GRADO 1

$$0 \quad \varphi: \mathbb{R} \rightarrow \mathbb{R}^2 \text{ linear? } \Leftrightarrow$$

$$\varphi(x) = \begin{pmatrix} a_1 x \\ a_2 x \end{pmatrix} \quad (\text{io } \rightarrow \text{MAPPA } \mathbb{R} \rightarrow \mathbb{R}^2)$$

$$\varphi: \mathbb{R} \rightarrow \mathbb{R}^2 \quad \frac{d\varphi}{dx}(x) = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \varphi'(x) \quad x \in \mathbb{R}$$

$$= \sum_{i=1}^n \frac{\partial f_i}{\partial x_j} dx_j$$

$$\text{Covarianza di } f \text{ (es) } \frac{d^2 f}{dx^2} = \frac{\partial^2 f}{\partial x_i^2}$$

$$f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}, \quad A \text{ aperto connesso}$$

$$df(x) \text{ parametrizzabile } \Leftrightarrow \frac{d^2 f}{dx^2} \in \mathbb{R}^n \times \mathbb{R}^n \quad \forall x \in A$$

$$\text{Es: } f: \mathbb{R}^3 \rightarrow \mathbb{R} \quad f(x, y, z) = 3x^2 - xy^2 + 3z$$

$$f \text{ differenziabile } \Rightarrow f \text{ continua (e viceversa)}$$

$$f(A) \stackrel{!}{=} \sum_{x \in A} df(x) \in \mathbb{R}^n \quad \text{si ha}$$

$$\frac{\partial f}{\partial x}(x, y, z) = 6xy - y^2 \Rightarrow \frac{\partial f}{\partial x}(1, -1, 1) = -6 - 1 = -7$$

$$\frac{\partial f}{\partial y}(x, y, z) = 3x^2 - 2xy \Rightarrow \frac{\partial f}{\partial y}(1, -1, 1) = 3 + 2 = 5$$

$$\frac{\partial f}{\partial z}(x, y, z) = 3 \Rightarrow \frac{\partial f}{\partial z}(1, -1, 1) = 3 \quad (-7, 5, 3)$$

$$df(x) = -7 dx + 5 dy + 3 dz$$